

Automating Geometry Construction Problems

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ArgoTriCS

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Geometry constraint solving

- **Geometric constraint solving** involves determining the positions of geometric elements (points, lines, circles) that meet a specified set of constraints
- Constraints considered include distances, incidences, tangencies, etc.
- One of central tasks is reasoning about **constructibility** – ability to achieve a given configuration with specific tools
- **Geometric construction solving** is a special case of geometric constraint solving

Geometry construction problems

- One of the most studied (and most challenging) problems in math education
- Require visualization, precision, abstract way of thinking
- The task is to describe a construction of a geometric figure that meets given constraints
- Constructions are **procedures**

Phases in solving construction problems

- **Analysis**: analyzing the figure to be constructed and finding key properties for construction
- **Construction**: identifying the sequence of steps used to construct the figure
- **Proof**: proving that the constructed figure satisfies the problem specification
- **Discussion**: analyzing when and how many solutions exist

Constructions using straightedge and compass

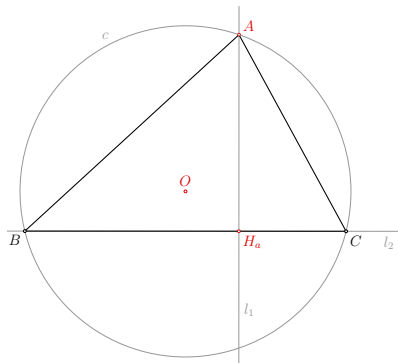
- Tools: **straightedge and compass**
- Elementary steps:
 - ▶ construction of an arbitrary point
 - ▶ construction of a line through two given points
 - ▶ construction of a circle centered at given point passing through another point
 - ▶ construction of an intersection of two circles, two lines, or a line and a circle
- We usually use also compound construction steps

Location triangle construction problems

- Construction problems may use locational data (positions) or non-locational data (lengths, angles, ratios)
- The first type of problems is known as **location construction problems**
- **Triangle construction problems** require constructing a triangle that meets given conditions
- Triangle construction problems are easy to state, but challenging to solve
- They play important role in both educational context and real-world applications
- In this talk we focus on triangle location construction problems

Motivating example

- **Example:** Construct a triangle ABC given locations of
 - ▶ its vertex A
 - ▶ its altitude foot H_a
 - ▶ its circumcenter O
- **Solution:** A, H_a, O



- 1 Construct the line l_1 through points A and H_a
- 2 Construct the perpendicular l_2 to line l_1 through H_a
- 3 Construct the circle c centered at O passing through A
- 4 Construct points B and C as the intersection points of l_2 and c

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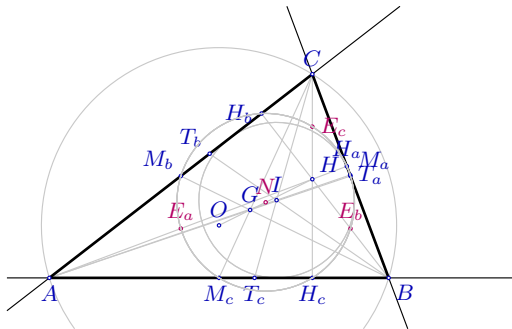
Towards automating constructions

- The main problem in solving:
combinatorial explosion – huge search space
 - ▶ many different construction steps available
 - ▶ plenty of objects that each step could be applied to
- Some instances are unsolvable (e.g. angle trisection)
- Having automated tool for construction solving is important for many reasons
- However, there are only a few tools for automating constructions (Schreck; Chou, Gao, Zhang; Gulwani)

- ArgoTriCS – Argo Triangle Construction Solver
- System for automated solving of location construction problems from the given corpus
- Primarely focused on triangle construction problems:
constructing $\triangle ABC$ if locations of three significant points in the triangle are given
- It can be applied to other types of construction problems, also
- Developed in Prolog
- Based on systematization of background geometrical knowledge needed

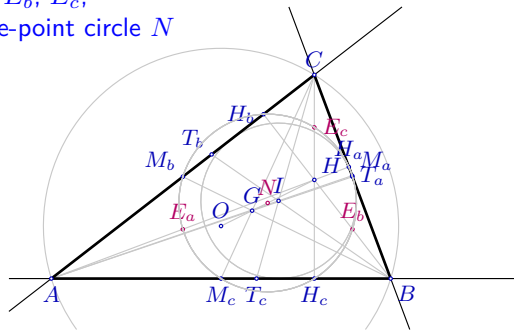
Corpora of triangle location construction problems

- Wernick's corpus (1982)
 - ▶ vertices A, B, C ,
 - ▶ side midpoints M_a, M_b, M_c ,
 - ▶ feet of altitudes H_a, H_b, H_c ,
 - ▶ feet of internal angle bisectors T_a, T_b, T_c .
 - ▶ orthocenter H , centroid G , circumcenter O , incenter I ,



Corpora of triangle location construction problems

- Wernick's corpus (1982)
- Connelly's corpus, extension of Wernick's corpus (2009)
 - ▶ vertices A, B, C ,
 - ▶ side midpoints M_a, M_b, M_c ,
 - ▶ feet of altitudes H_a, H_b, H_c ,
 - ▶ feet of internal angle bisectors T_a, T_b, T_c ,
 - ▶ orthocenter H , centroid G , circumcenter O , incenter I ,
 - ▶ Euler points E_a, E_b, E_c ,
 - ▶ the center of nine-point circle N



Possible statuses of construction problems

- Construction problems can be
 - ▶ solvable – $S(A, B, M_a)$
 - ▶ unsolvable – $U(T_a, T_b, T_c)$
 - ▶ redundant – $R(A, B, M_c)$
 - ▶ locus-dependent – $L(A, B, O)$

Algorithm for solving geometric construction problems

- Search starts from the objects given
- Search stops once all vertices are constructed or there are no more applicable primitive constructions
- Iterative procedure with forward chaining
- Primitive constructions are applied in a waterfall manner
- Objects that can be constructed are only relevant ones
- Obtained proof-trace is filtered-out and only relevant steps are preserved in the clean proof

Solution to geometric construction problem

- Informal description of construction in NL form
- Formal specification of construction in GCLC language and JSON format
- Static illustration in GCLC tool with step-by-step animation
- Dynamic illustration using ArgoDG library
- Construction correctness proof obtained by
 - ▶ OpenGeoProver (Wu's method)
 - ▶ Provers within GCLC tool (area method, Gröbner basis method and Wu's method)
- Non-degeneracy conditions under which the solution exists
- Determination conditions under which the solution is uniquely determined

Example construction in NL form and in GCLC

Problem: Given points A , O , and H_a construct the triangle ABC .

Construction:

- 1 Construct the line h_a through points A and H_a ;
- 2 Construct the perpendicular a to line h_a through point H_a ;
- 3 Construct the circle $\mathcal{C}_c$ with center at point O passing through point A ;
- 4 Construct the intersection points B and C of circle $\mathcal{C}_c$ and line a .

NDG conditions: line a and circle $\mathcal{C}_c$ intersect; points A and O are not the same.

Determination conditions: points A and H_a are not the same.

Example construction in GCLC and corresponding illustration

WinGCLC - [construction_32.gcl]

File Edit Source Picture View Window Help

```
dim 120 120
point A 80 95
point O 65 51.14
point H_{a} 80 40

color 220 0 0
fontsize 9

cmark_r A
cmark_r O
cmark_r H_{a}
color 0 0 0
fontsize 8

% DET: points A and H_{a} are not the same
% Constructing a line h_{a} which passes through
line h_{a} A H_{a}

color 200 200 200
drawline h_{a}
color 0 0 0

% NDG: points A and O are not the same
% Constructing a circle k(O,C) whose center is
circle k(O,C) O A

color 200 200 200
drawcircle k(O,C)
```

Total number of proof steps: 0
Time spent by the prover: 0.001 seconds
The conjecture not proved.

Ready

Ln 23, Col 1 x=-95.30 y=99.50 Zoom:1.00 NUM

The illustration shows a geometric construction in a coordinate plane. A circle $k(O, C)$ is centered at point $O(65, 51.14)$ and passes through point $A(80, 95)$. A line h_a is drawn passing through points $A(80, 95)$ and $H_a(80, 40)$. The construction is visualized within a white rectangular frame on a gray background. The line h_a is drawn in red, and the circle $k(O, C)$ is drawn in black. The points A , O , and H_a are marked with red dots. The line h_a is vertical, passing through A and H_a . The circle $k(O, C)$ is centered at O and passes through A .

Evaluation of construction generation using ArgoTriCS

- Solved 66 out of 74 solvable problems from Wernick's corpus and 62 out of 74 from Connelly's corpus
- Detected all redundant and locus-dependent construction problems
- Longest generated construction has 19 construction steps
- For some solvable problems that ArgoTriCS failed to solve, there are no synthetic solutions in the literature
- Automatically generated compendium of solutions to problems from Wernick's and Connelly's corpora available online
<http://poincare.matf.bg.ac.rs/~vesnap/animations/compendiums.html>

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Proving unconstructibility

- So far, we were focused solely on **solving** construction problems
- In schools, also, an emphasize is usually put on solvable construction problems
- How do we know if a construction problem is solvable?
- What about **unsolvable** construction problems?
- Proofs of RC-unconstructibility are usually performed using algebraic methods
- Even with modern computer algebra systems, it remains challenging

Computer assisted resolving of status of problems

- We focused on determining the status of problems from Wernick's and Connelly's corpora
- In the original Wernick's list, 41 problems were with unknown status, while two problems were incorrectly classified
- In the meanwhile only 15 problems from Wernick's list remained with unknown status
- Automatic tool in Maple, based on algebraization of geometric constructions and Galois theory, resolved status of **all** problems in Wernick's list (P. Schreck, P. Mathis)
- The status of **all** problems from Connelly's corpus was also determined, by using additional preprocessing for some problems

Statistics of Wernick's and Connely's corpora

- Wernick's corpus: in total $\binom{16}{3} = 560$ instances, 139 non-trivial, significantly different problems; 3 **redundant** (R); 23 **locus dependent** (L); 74 **solvable** (S); 39 **unsolvable** (U)

1. A, B, O	L	57. A, H, I S [9]	85. M_a, M_b, H_c S	113. M_a, T_b, T_c
2. A, B, M_a	S	58. A, T_a, T_b S [9]	86. M_a, M_b, H_c S	114. M_a, T_b, I U [9]
3. A, B, M_c	R	59. T_a, I L	87. M_a, M_b, H_c S [9]	115. G, H_a, H_b U [9]
4. A, B, G	S	60. T_b, T_c S	88. M_a, M_b, T_a U [9]	116. G, H_a, H S
5. A, B, H_a	L	61. I S	89. M_a, M_b, T_c U [9]	117. G, H_a, T_a S
6. A, B, H_c	L	62. M S	90. M_a, M_b, I U [10]	118. G, H_a, T_b
7. A, B, H	S	63. G S	91. M_a, G, H_c L	119. G, H_a, I
8. A, B, T_a	S	64. T_a L	92. M_a, G, H_b S	120. G, H, T_a U [9]
9. A, B, T_c	S	65. S	93. M_a, G, H S	121. G, H, I U [9]
		66. L	94. M_a, G, T_a S	122. G, T_a, T_b
		67. U [9]	95. M_a, G, T_b U [9]	123. G, T_a, I
		68. S	96. M_a, G, I S [9]	124. H_a, H_b, H_c S
		69. S	97. M_a, H_a, H_b S	125. H_a, H_b, H S
		70. R	98. M_a, H_a, H L	126. H_a, H_b, T_a S
		71. U [9]	99. M_a, H_a, T_a L	127. H_a, H_b, T_c
		72. U [9]	100. M_a, H_a, T_b U [9]	128. H_a, H_b, I
		73. H_b S [9]	101. M_a, H_a, I S	129. H_a, H, T_a L
		74. H S	102. M_a, H_b, H_c L	130. H_a, H, T_b U [9]
		75. H S	103. M_a, H_b, H S	131. H_a, H, I S [9]
		76. H_a, T_b S	104. M_a, H_b, T_a S	132. H_a, T_a, T_b
		77. H_a, T_b	105. M_a, H_b, T_b S	133. H_a, T_a, I S
		78. H_a, I	106. M_a, H_b, T_c U [9]	134. H_a, T_b, T_c
		79. O, H, T_a U [9]	107. M_a, H_b, I U [9]	135. H_a, T_b, I
		80. O, H, I U [9]	108. M_a, H, T_a U [9]	136. H, T_a, T_b
		81. O, T_a, T_b	109. M_a, H, T_b U [10]	137. H, T_a, I
26. A, M_a, I	S [9]	82. O, T_a, I S [9]	110. M_a, H, I U [10]	138. T_a, T_b, T_c U [11]
27. A, M_a, I	S [9]	83. M_a, M_b, M_c S	111. M_a, T_a, T_b U [10]	139. T_a, T_b, I S
28. A, M_b, M_c	S	84. M_a, M_b, G S	112. M_a, T_a, I S	

- Connelly's corpus: 580 new instances, 140 non-trivial, significantly different problems; 5 **redundant** (R); 19 **locus dependent** (L); 74 **solvable** (S); 42 **unsolvable** (U)

Proving (un)constructibility by reduction

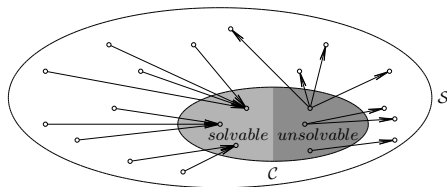
- Determining the status of one problem can be **reduced** to determining the status of another
- Let us concentrate on triangle construction problems from Wernick's corpus
- There is a **reduction** from triangle construction problem $P : (A_1, A_2, A_3)$ to problem $P' : (A'_1, A'_2, A'_3)$ if each point from P' **can be constructed** using the points from P
- It holds:
 - ▶ if P' is **S**, then P is also **S**; if P is **U**, then P' is either **U** or **R** or **L**
 - ▶ if P is **L**, then P' is **R** or **L**; if P is **R**, then P' is also **R**

Production rules

- How to effectively find reductions between triangle construction problems?
- If, given a set of significant points S , a significant point X is constructible, we say that there is a **production rule** $S \rightarrow X$
- For instance: $\{A, B\} \rightarrow M_c$, $\{A, H, T_a, I\} \rightarrow B$
- In this way the reduction phase boils down to a simple syntactical procedure
- Production rules can be derived using ArgoTriCS, starting from $k = 2, 3, 4$ points and trying to construct remaining $16 - k$ significant points

Constructibility classes of construction problems

- The goal is to find **minimal** subset $\mathcal{C}$ of the set of construction problems $\mathcal{S}$ that satisfies:
 - ▶ for each problem $P \in \mathcal{S}$ that is **S**, there is a problem $P' \in \mathcal{C}$ such that P' can be obtained from P by application of production rules
 - ▶ for each problem $P \in \mathcal{S}$ that is **U**, there is a problem $P' \in \mathcal{C}$ such that P can be obtained from P' by application of production rules
- The problems from $\mathcal{C}$ are key problems
- The problem reduces to a set covering problem, solvable by SAT-based system URSA
- URSA returned the set $\mathcal{C}$ consisting of 9 **S** problems and 33 **U** problems



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Solving construction problem as proving a theorem

- Solving construction problems can be approached from the logical point of view
- It corresponds to **proving constructively a theorem** of the form:

$$\forall X. \exists Y. \Psi(X, Y)$$

- Witness for Y represents a construction of a solution and must involve only points that are constructible from X
- Some construction problems have solutions only under some additional assumptions
- The complete characterization of solvability requires proving the following theorem:

$$\forall X. (\Phi(X) \Leftrightarrow \exists Y. \Psi(X, Y))$$

- $\Phi(X)$ denote constraints on given objects X , not known in advance

Solving construction problems as proving theorems

- Problem of constructing $\triangle ABC$ given its vertex A , altitude foot H_a , and circumcenter O is translated into the following theorem:

$$\begin{aligned} \forall A, H_a, O. (\Phi(A, H_a, O) \Leftrightarrow & \exists B, C. (\neg collinear(A, B, C) \\ & \wedge altitude_foot(H_a, A, B, C) \wedge circumcenter(O, A, B, C))) \end{aligned}$$

- $\Phi(A, H_a, O)$ has to be discovered, while $\neg collinear(A, B, C)$ is implicit goal condition

Machine-verifiable solutions to construction problems

- Generation of formal solutions to construction problems requires synergy of tools:
 - ▶ tool for solving constructions – used for construction phase
 - ▶ algebraic theorem provers – used for proving phase
 - ▶ synthetic automated theorem provers – used for analysis and proof phase
 - ▶ interactive theorem provers – used for gluing obtained proof fragments
- Formal proofs for a subset of problems from Wernick's corpus are obtained
- Two gaps:
 - ▶ link to external algebraic provers
 - ▶ using higher-order lemmas as axioms

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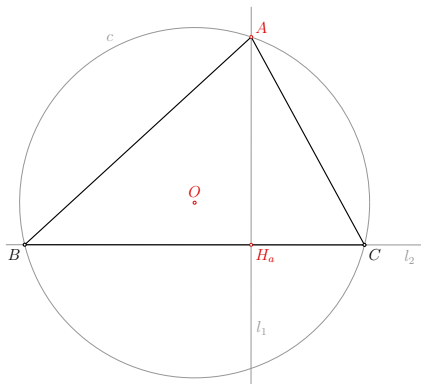
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Proving constructions correct

- Most of existing systems for automated solving geometric constructions **do not** consider proving generated constructions correct
- Proving triangle construction correct means proving that the points given by problem setting are indeed the corresponding points of the constructed triangle

Motivating example – construction phase

- **Task:** Construct $\triangle ABC$ given its vertex A , altitude foot H_a , and circumcenter O

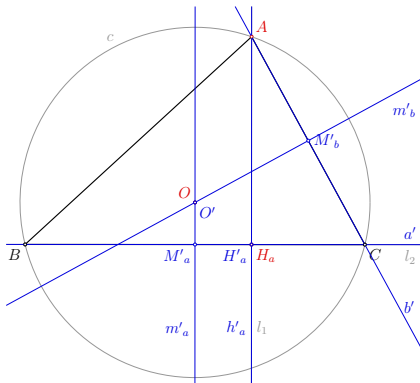


- 1 Construct the line l_1 through points A and H_a
- 2 Construct the perpendicular l_2 to line l_1 through H_a
- 3 Construct the circle c centered at O containing A
- 4 Construct points B and C as the intersection points of l_2 and c

- **Solution:** A, H_a, O

Motivating example – correctness conjecture

- ArgoTriCS generates correctness conjectures that can be passed to automated provers
- We should prove that for constructed $\triangle ABC$, A is its vertex, H_a is its altitude foot and O is circumcenter



- 1 Construct the line b' through points A and C
- 2 Construct the midpoint M'_b of the segment AC
- 3 Construct the line a' through points B and C
- 4 Construct the midpoint M'_a of the segment BC
- 5 Construct the perpendicular m'_a to a' through M_a
- 6 Construct the perpendicular m'_b to b' through M_b
- 7 Construct the intersection point O' of m'_a and m'_b
- 8 Construct the perpendicular h'_a to a' through A
- 9 Construct the intersection point H'_a of a' and h'_a
- 10 Prove that O is identical to O'
- 11 Prove that H_a is identical to H'_a

Algebraic and semi-synthetic proofs

- **Algebraic methods** (Wu's method, Gröbner basis method) – very efficient, but non-readable
- **Semi-synthetic methods** (area method) – readable proofs, but formulated in non-traditional terms

5.9 Triangulation, step 9

Choosing variable: Trying the variable with index 4.

Variable x_4 selected: The number of polynomials with this variable is 2.

Minimal degrees: 2 polynomials with degree 1 and 3 polynomials with degree 2.

Polynomial with linear degree: Removing variable x_4 from all other polynomials by reducing them with polynomial p_3 .

Finished a triangulation step, the current system is:

$$\begin{aligned} p_0 &= u_2x_2 + u_3x_1 + (-u_3^2 - u_2^2) \\ p_1 &= x_2^2 - 2u_1x_2 + x_1^2 \\ p_2 &= x_3^2x_2^2 - 2u_2x_3^2x_2 + x_3^2x_1^2 - 2u_3x_3^2x_1 + \\ &\quad (u_3^2 + u_2^2)x_3^2 - 2u_3x_3x_2^2 + (2u_2 - 2u_1)x_3x_2x_1 + (2u_3u_2 + 2u_3u_1)x_3x_2 + \\ &\quad (-2u_2^2 + 2u_2u_1)x_3x_1 - 2u_3u_2u_1x_3 + u_3^2x_2^2 + \\ &\quad (-2u_3u_2 + 2u_3u_1)x_2x_1 - 2u_3^2u_1x_2 + (u_2^2 - 2u_2u_1)x_1^2 + 2u_3u_2u_1x_1 \end{aligned}$$

$$\begin{aligned} p_4 &= -x_6x_1 + x_5x_2 \\ p_5 &= -x_6 + 0.5x_2 \\ p_6 &= -x_8x_3 + x_8x_1 + x_7x_4 - x_7x_2 - x_4x_1 + x_3x_2 \\ p_7 &= -x_8 + 0.5x_4 + 0.5x_2 \\ p_8 &= -x_{10}x_4 + x_{10}x_2 - x_9x_3 + x_9x_1 + x_8x_4 - x_8x_2 + x_7x_3 - x_7x_1 \\ p_9 &= x_{10}x_2 + x_9x_1 - x_6x_2 - x_5x_1 \\ p_{10} &= -x_{12}x_4 + x_{12}x_2 - x_{11}x_3 + x_{11}x_1 \\ p_{11} &= x_{12}x_3 - x_{12}x_1 - x_{11}x_4 + x_{11}x_2 + x_4x_1 - x_3x_2 \end{aligned}$$

1. Creating S-polynomial from the pair (p_0, p_1) .

Forming S-pol of p_0 and p_1 :

$$p_{411} = u_3x_2x_1 + (-u_3^2 - u_2^2 + 2u_2u_1)x_2 - u_2x_1^2$$

S-pol added.

$$\begin{aligned} &P_{H_a-H_aH_a} = 0 \text{ by the statement} \\ &\left(\left(\left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot P_{H_aCH_a} \right) + \left(\frac{\overrightarrow{H_a-C}}{\overrightarrow{B-C}} \cdot P_{H_aBH_a} \right) \right) + \left(-1 \cdot \left(\left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot \frac{\overrightarrow{H_a-C}}{\overrightarrow{B-C}} \right) \cdot P_{BCB} \right) \right) \right) = 0 \text{ by Lemma 32} \\ &\left(\left(\left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot P_{H_aCH_a} \right) + \left(-1 \cdot \frac{\overrightarrow{C-H_a}}{\overrightarrow{B-C}} \cdot P_{H_aBH_a} \right) \right) + \left(-1 \cdot \left(\left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot \left(-1 \cdot \frac{\overrightarrow{C-H_a}}{\overrightarrow{B-C}} \right) \right) \cdot P_{BCB} \right) \right) \right) = 0 \text{ by geometric simplifications} \\ &\left(\left(\left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot P_{H_aCH_a} \right) + \left(-1 \cdot \left(\frac{\overrightarrow{C-H_a}}{\overrightarrow{B-C}} \cdot P_{H_aBH_a} \right) \right) \right) + \left(\frac{\overrightarrow{B-H_a}}{\overrightarrow{B-C}} \cdot \left(\frac{\overrightarrow{C-H_a}}{\overrightarrow{B-C}} \cdot P_{BCB} \right) \right) \right) = 0 \text{ by algebraic simplifications} \end{aligned}$$

Success rates in proving Wernick's problems

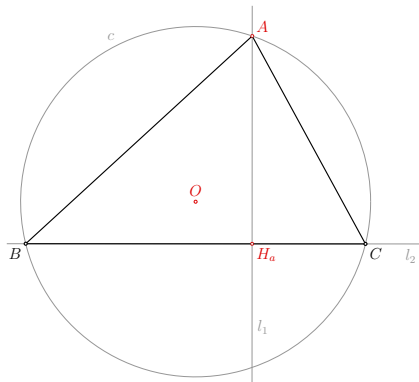
- We focused on problems from Wernick's corpus, solvable by ArgoTriCS
- Four different provers were used
 - ▶ provers integrated in GCLC (area method, Wu's method, and Gröbner bases method)
 - ▶ OpenGeoProver (Wu's method)
- OpenGeoProver was the most successful
- We worked also on portfolio approach, by choosing one particular solver for a specific correctness conjecture

Readability and understandability of proofs

- None of these correctness proofs don't look like classical, human-readable, synthetic proofs
- Readability is vital for educational purposes
- ArgoTriCS can be combined with CL provers to automatically obtain **traditional, readable correctness proofs**

Motivating example – readable proof

- Prove that A is the vertex of the constructed $\triangle ABC$, H_a is its altitude foot and O is its circumcenter



- 1 c_c contains vertices A , B , and C ,
so it must be the circumcircle of $\triangle ABC$
- 2 O is the center of c_c ,
so it must be the circumcenter of $\triangle ABC$
- 3 a contains the vertices B and C ,
so it must be the side BC of $\triangle ABC$
- 4 h_a contains A and is perpendicular to a ,
so it must be the altitude from vertex A
- 5 H_a belongs both to triangle side a and triangle altitude h_a , so it must be the altitude foot

Lessons following from previous example

- The previous correctness proof is readable
- It follows quite directly from the analysis: it just reverses the chain of deduction steps
- The proof relies on several uniqueness lemmas
- One could assume that proving correctness is always easy like this, however...
- ... in some cases the **proof is quite different from the analysis**

Automated generation of readable correctness proofs

- How can readable correctness proofs be **automatically** obtained?
- ArgoTriCS can automatically export the TPTP file containing:
 - ▶ the correctness conjecture
 - ▶ the set of axioms corresponding to the geometric definitions and lemmas
- It can be further passed to an automated theorem prover
- To be able to prove the correctness conjecture, apart from lemmas identified during development of ArgoTriCS, additional lemmas are needed
- Are there automated provers that can
 - ▶ prove these types of conjectures?
 - ▶ produce readable proofs?
 - ▶ possibly produce formal proofs?

Automated theorem provers based on coherent logic

- **Coherent logic** is a fragment of FOL convenient for producing readable proofs

$$A_1(\vec{x}) \wedge \dots \wedge A_n(\vec{x}) \Rightarrow \exists \vec{y}_1 \mathcal{B}_1(\vec{x}, \vec{y}_1) \vee \dots \vee \exists \vec{y}_m \mathcal{B}_m(\vec{x}, \vec{y}_m)$$

- **ArgoCLP** is a coherent logic (CL) prover that can export both readable and formal proofs
- **Larus** is a CL prover that can export both readable and formal proofs (Janičić, Narboux)
- **GCProuver** is a prover based on fragment of CL without disjunctions and existential quantifiers
- Correctness conjectures fall into this reduced fragment of CL, so each of these provers can be used

Example of automatically generated readable correctness proof

Axioms:

- ① $\text{bc_unique} : \forall L \ (inc(pB, L) \wedge inc(pC, L) \Rightarrow L = bc)$
- ② $\text{haA} : \forall H \ (perp(H, bc) \wedge inc(pA, H) \Rightarrow ha = H)$
- ③ $\text{pHa_def} : \forall H1 \ (inc(H1, ha) \wedge inc(H1, bc) \Rightarrow H1 = pHa)$
- ④ $\text{cc_unique} : \forall C \ (inc_c(pA, C) \wedge inc_c(pB, C) \wedge inc_c(pC, C) \Rightarrow C = cc)$
- ⑤ $\text{center_unique} : \forall C \ \forall C1 \ \forall C2 \ (center(C1, C) \wedge center(C2, C) \Rightarrow C1 = C2)$

Theorem: th_A_Ha_O0 :

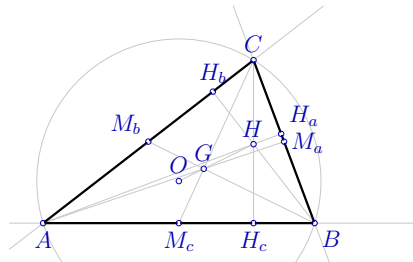
$inc(pA, ha1) \wedge inc(pHa1, ha1) \wedge perp(ha1, a1) \wedge inc(pHa1, a1) \wedge inc_c(pA, cc1) \wedge center(pOc1, cc1) \wedge inc_c(pB, cc1) \wedge inc(pB, a1) \wedge inc_c(pC, cc1) \wedge inc(pC, a1) \Rightarrow pHa = pHa1$

Proof:

1. $pHa = pHa$ (by MP, using axiom eqnativeEqSub0; instantiation: $A \mapsto pHa, B \mapsto pHa, X \mapsto pHa$)
2. $a1 = bc$ (by MP, from $inc(pB, a1), inc(pC, a1)$ using axiom bc_unique; instantiation: $L \mapsto a1$)
3. $perp(ha1, bc)$ (by MP, from $perp(ha1, a1), a1 = bc$ using axiom perpEqSub1; instantiation: $A \mapsto ha1, B \mapsto a1, X \mapsto bc$)
4. $ha = ha1$ (by MP, from $perp(ha1, bc), inc(pA, ha1)$ using axiom haA; instantiation: $H \mapsto ha1$)
5. $inc(pHa1, ha)$ (by MP, from $inc(pHa1, ha1), ha = ha1$ using axiom incEqSub1; instantiation: $A \mapsto pHa1, B \mapsto ha1, X \mapsto ha$)
6. $inc(pHa1, bc)$ (by MP, from $inc(pHa1, a1), a1 = bc$ using axiom incEqSub1; instantiation: $A \mapsto pHa1, B \mapsto a1, X \mapsto bc$)
7. $pHa1 = pHa$ (by MP, from $inc(pHa1, ha), inc(pHa1, bc)$ using axiom pHa_def; instantiation: $H1 \mapsto pHa1$)
8. $pHa = pHa1$ (by MP, from $pHa1 = pHa, pHa = pHa$ using axiom eqnativeEqSub0; instantiation: $A \mapsto pHa, B \mapsto pHa1, X \mapsto pHa$)
9. Proved by assumption! (by QEDas)

Evaluation of effectiveness of Larus and GCProver

- The subset of Wernick's corpus is considered over:
 - ▶ vertices A, B, C
 - ▶ side midpoints M_a, M_b, M_c
 - ▶ feet of altitudes H_a, H_b, H_c
 - ▶ centroid G , circumcenter O and orthocenter H
- 35 non-isomorphic solvable problems



- Larus proved 20 problems, while GCProver proved all 35 correctness conjectures within the time-limit of 300s
- It often needed guidance to prove the correctness conjectures
- Unlike GCProver, Larus outputs also formal proofs in Coq and Isabelle/HOL

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Status of proofs

- Correctness of background geometric knowledge used by ArgoTriCS has, until now, been **taken for granted**
- Obtained correctness proofs currently rely on high-level lemmas
`fof(ratio23_AGAMa, axiom, (ratio23(pA,pG,pA,pMa)))`.
- To be sure in validity of those proofs, correctness of used lemmas should be proved

Formalization of lemmas

- We are working on formalization of common geometric lemmas used as axioms within GCMProver (Pierre Boutry)
- Lemmas are being proved from the Tarski's axioms of Euclidean geometry, using GeoCoq
- Up to now, 55 out of 144 lemmas are proved
- Most of the remaining 89 lemmas are about:
 - ▶ ratio of lengths of directed segments
 - ▶ equality of non-primitive objects, such as lines and circles
 - ▶ asserting the existence of geometrical objects
- Work in progress

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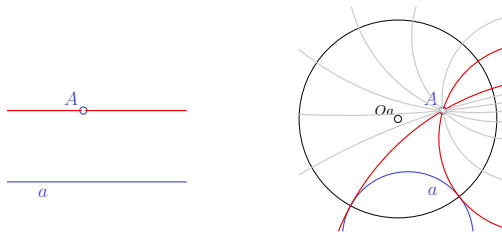
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Different geometries

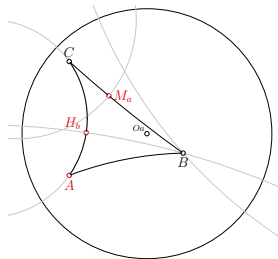
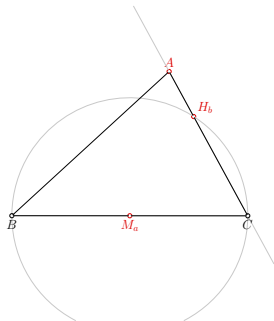
- Until now we considered the most common type of geometry – Euclidean geometry
- **Absolute geometry** is based on four axioms groups: incidence, order, congruence, and continuity
- By adding the appropriate axiom of parallelism, we get:
 - ▶ **Euclidean geometry**: a unique line parallel to a line a through a point A not on the line
 - ▶ **Hyperbolic geometry**: infinitely many parallels to a line a through a point A not on the line



- Challenge: automatically find constructions in absolute and hyperbolic geometry.

Automating constructions in hyperbolic geometry

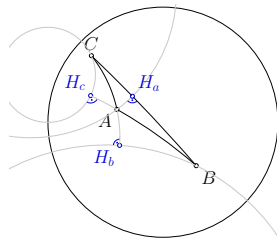
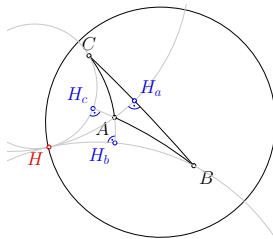
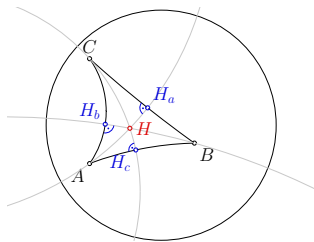
- ArgoTriCS was initially focused solely on Euclidean geometry
- Many ruler and compass constructions are valid only in Euclidean geometry



- ArgoTriCS can be adjusted to hyperbolic geometry by **solely** adapting geometric knowledge
- The first study on automated triangle constructions in hyperbolic geometry

Differences in geometric knowledge between Euclidean and hyperbolic case

- The centroid of the triangle does not divide the median in 2:1 ratio
- The inscribed angle subtended by a diameter need not be right
- The circumcenter and the orthocenter of a triangle need not exist



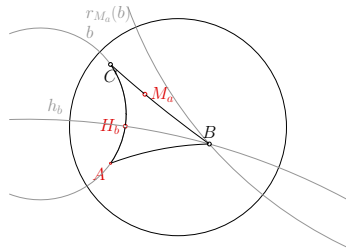
- Reflections play the most important role in hyperbolic solving

Example construction in hyperbolic geometry

Problem: Construct the triangle ABC given the vertex A , side midpoint M_a , and altitude foot H_b .

Construction:

- 1 Construct the line b through the points A and H_b ;
- 2 Construct the line h_b perpendicular to the line b through H_b ;
- 3 Construct the line $s_{M_a}(b)$ that is image of the line b under the reflection wrt. point M_a ;
- 4 Construct the intersection point B of the lines $s_{M_a}(b)$ and h_b ;
- 5 Construct the point C symmetric to B wrt. point M_a .



Evaluation of Construction Generation in Hyperbolic Geometry

- We considered the Wernick's corpus of construction problems
- From 139 significantly different problems, ArgoTriCS solved 31 solvable problems, 1 redundant and 11 locus dependent
- Automatically generated compendium of solutions to problems in hyperbolic geometry:
http://poincare.matf.bg.ac.rs/~vesnap/animations_hyp/compendium_wernick_hyperbolic.html

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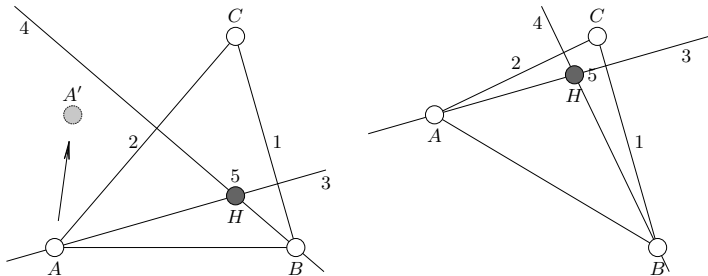
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Dynamic geometry tools

- **Dynamic geometry tools** appeared at late 20th century
- Provoked big changes in educational practices:
 - ▶ Enables visualisation
 - ▶ Allow real-time experimentations
- Through years they were integrated with automated theorem proving tools used for validation of properties, proof verification, etc.
- They became an important component of mathematical education

Typical interactivity in dynamic geometry tools

- Usual scenario:
 - ▶ user chooses several free points
 - ▶ using them user constructs other geometric objects
 - ▶ user can move free point and explore how other (constructed) objects change by recomputing coordinates of constructed points

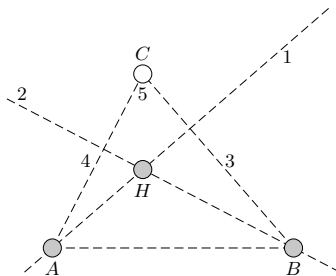
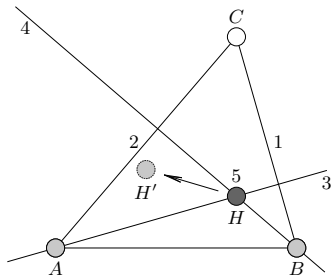


Moving constructed points

- Rather new scenario: **moving constructed point**
 - ▶ necessary to specify which points stay fixed
 - ▶ user can move only one of the significant points in triangle
 - ▶ reconstruction of location of all other objects in the triangle is performed by reconstruction of the coordinates of triangle vertices
- Reconstruction of triangle vertices given positions of significant points in triangle boils down to solving triangle construction problem, performed by ArgoTriCS
- This scenario is implemented in tool Touch&Drag for touch screens

Example of moving constructed points

- Vertices A, B and C are chosen freely, orthocenter H of $\triangle ABC$ is constructed
- Orthocenter H is moved, while vertices A and B stay fixed
- How to determine a new position of vertex C ?



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Next step guidance

- Help students once they get stuck and do not know how to proceed with the construction
- Enables interactivity and keeps student active participant of the learning process
- Different types of help:
 - ▶ suggest the next construction step
 - ▶ suggest an object (point, line, circle) that should be constructed
 - ▶ suggest a lemma that the construction relies on

Target construction

- There can be many possible constructions for the same problem
- Not all solutions are intuitive and easily comprehensible
- Example: A, B, H
 - ▶ A, B, H - solution 1
 - ▶ A, B, H - solution 2
- Next step guidance assumes that we select one **target construction** that is closest to the partial construction given by the student
- There are different approaches to choose it:
 - ▶ ArgoTriCS can find several possible constructions (in advance), compare them to the partial construction, and select the most adequate one
 - ▶ ArgoTriCS can be restarted given all the objects constructed by the partial construction

Suggestions

- Once the target construction is fixed, what should be suggested?
 - ▶ the next construction step
 - ★ A, B, H - solution 1
Suggestion: “construct a perpendicular to a known line through a known point”
 - ▶ an important auxiliary object (point, line, circle)
 - ★ A, B, H - solution 2
Suggestion: “construct circle over segment AB ”
 - ▶ an important lemma used in construction correctness proof
 - ★ A, B, H - solution 1
“altitudes are orthogonal to triangle sides ($h_a \perp a, h_b \perp b$)”.

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Conclusions

- At the intersection of all topics discussed is ArgoTriCS – a system for automating constructions
- Its focus is primarily on educational aspect, but keeping a level of rigor
- It is adaptable
 - ▶ can be used for both Euclidean and hyperbolic geometry
 - ▶ usually starts from three located points, but also can start from different number of different objects or non-locational data
 - ▶ can be integrated with algebraic provers, but also FOL and CL provers, as well as interactive theorem provers
 - ▶ can cooperate with dynamic geometry software
- Plans for the future: finishing NSG and lemma formalization, adding full support for LD problems, experimenting with origami

Thanks

- Thank you for your attention!